

## Pure visual imagery as a potential approach to achieve three classes of control for implementation of BCI in non-motor disorders

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3 **Pure visual imagery as a potential approach to achieve three classes of control**  
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6 **for implementation of BCI in non-motor disorders**  
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## 1 **Abstract**

2 *Objective:* The achievement of multiple instances of control with the same type of mental  
3 strategy represents a way to improve flexibility of BCI systems. Here we test the hypothesis that  
4 pure visual motion imagery of an external actuator can be used as a tool to achieve three classes  
5 of EEG based control, which might be useful in attention disorders.

6 *Approach:* We hypothesize that different number of imagined motion alternations lead to  
7 distinctive signals, as predicted by distinct motion patterns. Accordingly, distinct number of  
8 alternating sensory/perceptual signals would lead to distinct neural responses as previously  
9 demonstrated using fMRI. We anticipate that differential modulations should also be observed in  
10 the EEG domain. EEG recordings were obtained from twelve participants using three imagery  
11 tasks: imagery of a static dot, imagery of a dot with two opposing motions in the vertical axis (2  
12 motion directions) and imagery of a dot with four opposing motions in vertical or horizontal axes  
13 (4 directions). The data were analysed offline.

14 *Main results:* An increase of alpha-band power was found in frontal and central channels as a  
15 result of visual motion imagery tasks when compared with static dot imagery, in contrast with  
16 the expected posterior alpha decreases found during simple visual stimulation. The successful  
17 classification and discrimination between the three imagery tasks confirmed that three different  
18 classes of control based on visual motion imagery can be achieved. The classification approach  
19 was based on SVM and on the alpha-band relative spectral power of a small group of six frontal  
20 and central channels. Patterns of alpha activity, as captured by single-trial SVM closely reflected  
21 imagery properties, in particular the number of imagined motion alternations.

22 *Significance:* We found a new mental task based on visual motion imagery with potential for the  
23 implementation of multiclass (3) BCIs. Our results are consistent with the notion that frontal  
24 alpha synchronization is related with high internal processing demands, changing with the  
25 number of alternation levels during imagery. Together, these findings suggest the feasibility of  
26 pure visual motion imagery tasks as a strategy to achieve multiclass control systems with  
27 potential for BCI and in particular neurofeedback applications in non-motor (attentional)  
28 disorders.

29

30 **Keywords:** Multiclass control, visual motion imagery.

## 31 **Introduction**

32 Current neuroimaging technologies allow to investigate the neural correlates of perceptual  
33 operations. A deep understanding of such correlates may help design neural interfaces that use  
34 such signals in brain-computer interfaces (BCI) or neurofeedback approaches. In some non-  
35 motor diseases such as attentional disorders, self-centered state control, used in the more specific  
36 context of neurofeedback (Banca *et al* 2015, DeBettencourt *et al* 2015, Ordikhani-Seyedlar *et al*  
37 2016), is more important than speed of communication (as used in motor BCIs).

38 BCI approaches measure and convert brain signals into artificial outputs (Farwell and  
39 Donchin 1988, Wolpaw and McFarland 2004). These systems enable users to act on the world by  
40 using their brain signals rather than the brain's normal output pathways of peripheral nerves and  
41 muscles (Shih *et al* 2012). BCI systems can be applied as assistive BCIs or as neurofeedback  
42 approaches (Chaudhary *et al* 2016). Assistive BCIs aim to support the daily life of users with  
43 deficits of for example in motor or communication functions (McFarland and Wolpaw 2011). On  
44 the other hand, neurofeedback systems aim to facilitate the restoration of brain function and/or  
45 behavior or improve it by self-regulation of brain activity (Thibault *et al* 2016). While assistive  
46 BCIs are application centered (steering of a wheelchair, communication interface) neurofeedback  
47 systems are user centered (self-regulation and restoration of specific brain patterns).  
48 Furthermore, the scope of BCI research can include non-medical applications as user state  
49 monitoring and gaming (Lécuyer *et al* 2008).

50 Effective BCI communication or device control based on electroencephalographic (EEG)  
51 signals – EEG-based BCI – has been demonstrated using slow cortical potentials (Birbaumer *et*  
52 *al* 1999, Kubler *et al* 2001, Karim *et al* 2006), brain rhythms (Pfurtscheller *et al* 1997, Treder *et*  
53 *al* 2011, Ono *et al* 2014, McFarland *et al* 2015) or event-related potentials (Nijboer *et al* 2008,  
54 Baek *et al* 2013, Combaz and Van Hulle 2015). The most used EEG-based BCI inputs are  
55 sensory-motor rhythms (Leeb *et al* 2013, Ge *et al* 2014, Maria *et al* 2015, Ramos-Murguialday  
56 and Birbaumer 2015) and P300 evoked potentials (Pires *et al* 2012, Amaral *et al* 2015, Lopes *et*  
57 *al* 2016). Usually the BCI systems design emphasizes speed because the main goal is to provide  
58 motor or communication output, but applications targeting self state control, such as enabled by

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4 59 visual imagery (Banca *et al* 2015), might be useful for attentional disorders such as attention  
5 60 deficit hyperactivity disorder (ADHD) (Abraham *et al* 2006).

61 One of major goals of the current BCI research is to define novel tasks and approaches that  
62 can be used in non-motor disorders and increase the number of classes and the intrinsic number  
63 of levels of control, i.e. to increase the degrees of freedom. This would mainly allow to develop  
64 novel and more precise forms of neurofeedback. The conventional P300 paradigms generate  
65 various BCI commands allowing, for example, to move a wheelchair (Lopes *et al* 2016) or to  
66 generate a speller (Pires *et al* 2012). However, they associate commands to different stimuli  
67 presented to the subjects requiring all the time a stimulus to encode the attentional focus. BCI  
68 systems based on imagery are an alternative to the need of an external stimulus to encode the  
69 users' intention.

70 Human brain functions can be at least in part spatially localized, even in EEG, and thus  
71 separate commands can be encoded by taking advantage from information derived from  
72 functional modules evoking spatially distinct patterns of activity. This possibility is commonly  
73 used in BCI systems based on motor imagery, where the imagery of different motor actions (for  
74 example, leg or hand movement, right and left) produces spatially distributed brain activations  
75 (Ramos-Murguialday and Birbaumer 2015, Schlögl *et al* 2005). Although, the subjects usually  
76 receive instructions to imagine themselves performing a specific motor action without overt  
77 motor output, dependent on the exact manner of how subjects perform this task, the relative  
78 contribution of various aspects involved in motor imagery may vary and distinct neural processes  
79 may therefore be recruited.

80 Multiclass systems based on self-regulation of different brain rhythms combined or based on  
81 multilevel control of the same brain rhythm have already been explored. Wolpaw and McFarland  
82 suggested a multidimensional point-to-point movement control based on the combination of mu  
83 or beta rhythm amplitude modulation over the right and left sensorimotor cortices (Wolpaw and  
84 McFarland 2004). They showed that people can learn to use scalp-recorded EEG rhythms to  
85 move a cursor in two dimensions, and recently also in 3 dimensions (McFarland *et al* 2010). In  
86 another study, it was shown that self-regulation of slow cortical potentials can be reliably  
87 translated as two BCI commands (Karim *et al* 2006). More recently, a BCI study proposed an  
88 approach where participants were able to switch between modulation of alpha-band and gamma-  
89 band oscillations in the visual cortex (Salari and Rose 2013). However, for these particular

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3 90 studies the users' self-regulation of one specific brain rhythm allowed only two instances of  
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5 91 control. Furthermore, the described BCI approaches required some days of training.

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7 92 In this work we aim to test the possibility of obtaining three classes of control based on  
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9 93 evoked brain activity by pure visual motion imagery of an external actuator. Our hypothesis is  
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11 94 that using visual imagery strategies with different number of motion alternations it is possible to  
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13 95 achieve different patterns of brain activity modulation allowing for state related self-regulation  
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15 96 based multiclass control. From functional magnetic resonance imaging (fMRI) studies it is  
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17 97 known that in the visual motion perceptual domain conditions for which motion alternations  
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19 98 occur more often lead to stronger brain activity modulations (Tootell *et al* 1998, Huk and Heeger  
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21 99 2002, Larsson *et al* 2006, Sousa *et al* 2016). We use the imagery of three stimulation conditions  
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23 100 with different number of motion alternations (imagery of a static dot – no motion, imagery of a  
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25 101 dot with two opposing motions in the vertical axis – constant motion and, imagery of a dot with  
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27 102 four opposing motions in the vertical and horizontal axes – alternate motion) to test if using EEG  
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29 103 it is possible to distinguish three patterns of brain activity according to the level of imagined  
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31 104 motion alternation, as previously shown with fMRI (Sousa *et al* 2016). This would allow for the  
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33 105 implementation of a multilevel or at least a multiclass control EEG based approach mainly  
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35 106 depending on the applied imagery strategy irrespective of prior participant training. Furthermore,  
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37 107 in contrast to classical motor imagery strategies this approach is not influenced by participants'  
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39 108 movements and, in contrast to the P300 approaches does not depend on an external stimulus.

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41 109 Visual imagery refers to the emergence of constructive representations and the accompanying  
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43 110 perceptual experience without a direct external stimulus (Pearson *et al* 2015). This process plays  
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45 111 a core role in many mental health disorders, such as ADHD, anxiety, bipolar disorder and  
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47 112 schizophrenia, which may have therapeutic implications (Hackmann and Holmes 2004, Abraham  
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49 113 *et al* 2006, Holmes *et al* 2007, Brewin *et al* 2010; Holmes and Mathews 2010, Banca *et al* 2015).  
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51 114 Therefore, we expect that the present work might contribute to the discussion on feasibility of  
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53 115 multiclass self-regulation control for implementation in BCI methods, as well as on the potential  
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55 116 usefulness of finer control of visual imagery in mental disorders.

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57 117 In 2005 Neuper and colleagues explored the potential of visual-motor imagery as a control  
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59 118 strategy in comparison to motor imagery (Neuper *et al* 2005). They found that to improve BCI  
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119 control the user training should emphasize kinesthetic experiences instead of visual  
120 representations of actions, since only kinesthetic motor imagery, but not visual-motor imagery,

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3 121 resulted in detectable (versus baseline, and by a classifier) EEG changes. However, that study  
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5 122 focused on visual-motor imagery while we focused on pure visual imagery, which might be  
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7 123 potentially relevant for mental disorders such as the ones affecting attentional processes.  
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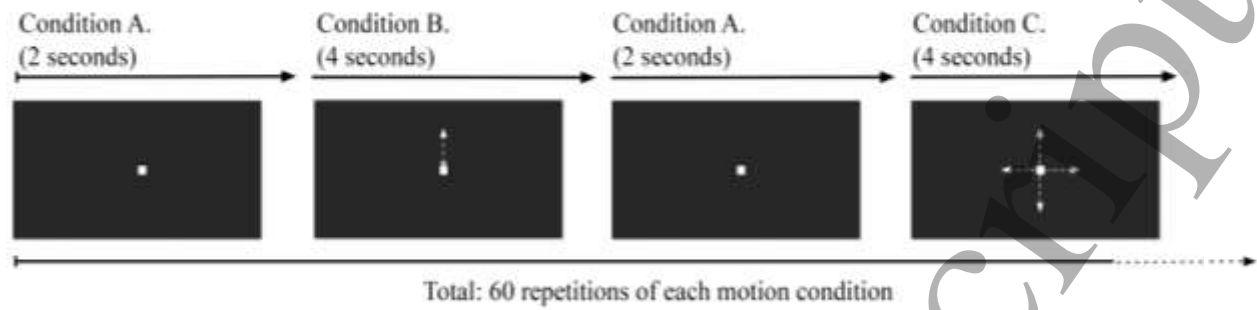
## 126 **Methods**

### 127 **Participants**

128 Twelve males participated in this study. On average, study participants were 28.9 years old (*SD*  
129 = 3.8 range 21-34 years). All participants were right-handed, had normal or corrected-to-normal  
130 vision and reported no medical or psychological disorders. Participants gave written informed  
131 consent prior to the EEG recording session. The procedure was approved by the Ethics  
132 Committee of the Faculty of Medicine of the University of Coimbra.  
133

### 134 **Experimental design**

135 The experiments were composed of two interleaved sessions in the same day: visual motion  
136 stimulation and visual motion imagery. The visual stimulation paradigm was used as a guide to  
137 the visual motion imagery tasks. During the visual stimulation session, participants were asked to  
138 fixate a central cross. As illustrated on figure 1, three different conditions were used: (A) zero  
139 motion (static dot), (B) a dot moving in two opposing directions (with constant vertical  
140 orientation – along y axis, less alternation, hereinafter referred as constant motion) and (C) a dot  
141 moving in four opposing directions (horizontal and vertical orientations – along x and y axes,  
142 more alternation, hereinafter referred as alternate motion). Four second trials of a moving dot (5  
143 deg/s) were randomly presented after each 2 seconds trial of a static dot. The distance covered by  
144 the dot was 2.5 degrees of arc. The motion conditions were repeated 60 times divided in two  
145 parts. The point size was  $0.5 \times 0.5 \text{ cm}^2$  (dot visual angle: 0.64 deg) and the stimulus was  
146 displayed at 44.5 cm from the participant at a screen of  $24.1 \times 18.2 \text{ cm}^2$ . Stimulus display and  
147 imagery instructions were controlled by MATLAB (MathWorks) using the Psychophysics  
148 toolbox (Brainard, 1997).  
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**Figure 1. Stimulation conditions.** (A) Static dot - static condition used as baseline to the motion conditions, (B) constant motion - moving dot alternating the direction, and (C) alternate motion - moving dot alternating the direction and the orientation. The arrows are here merely representing the dot motions. Each motion condition was repeated 60 times and randomly interleaved with the static dot condition. The duration of each motion condition was 4 seconds. Each static dot trial was presented only during 2 seconds.

In the visual motion imagery session, participants were asked to imagine the three previously presented stimulus conditions. The instruction for each imagery task was provided as an auditory cue coded as 'A', 'B' and 'C' respectively, and took one second. A beep sound was given to the participants 1.5 seconds after the beginning of each motion imagery task as a reminder of the spent imagery time.

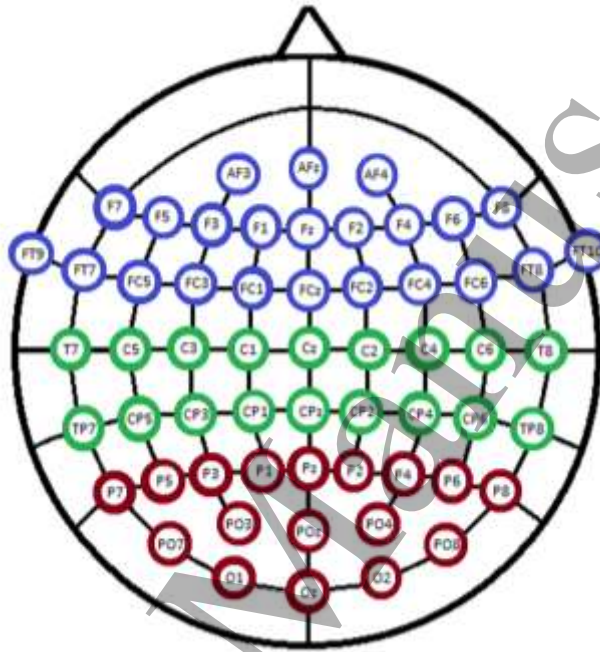
The duration and number of repetitions of each task were equal to the stimulation session ones. The imagery session was divided in two parts intercalated with stimulation (also divided in two parts) in order to decrease fatigue effects. Participants were seated comfortably in the darkened sound-attenuating EEG recording room and, were asked to breathe steadily and to remain as still as possible. Throughout the visual imagery tasks participants were also asked to close the eyes in order to prevent sources of visual noise. Although in real life implementations people should keep their eyes open, here we prioritized the optimization of signal to noise in our design of this proof-of-concept study, as already done in other visual imagery studies (De Pisapia *et al* 2016).

## Data acquisition

First, the participants scalp was cleaned using abrasive gel and then an actiCAP cap was placed on their heads. The EEG was recorded by means of a Brain Products Package (Brain Products, Germany) and sampled at a frequency of 1000 Hz. Ag/AgCl active electrodes (Brain Products), were located in 58 positions (according to the international 10-20 system with interspaced positions, figure 2), a ground electrode was located on the forehead and, two reference electrodes



176 were placed on the earlobes. The electrooculogram (EOG) was monitored via electrodes  
 177 positioned at the standard positions (vertical and horizontal) to be used in the correction of  
 178 artifacts due to blinking and eye movements. The signal was filtered between 0.1 Hz and 100 Hz  
 179 and an additional 50 Hz notch filter was applied to avoid power line contamination. Electrode  
 180 impedances were kept below 10 k $\Omega$  during the acquisitions.



181  
 182 **Figure 2. Layout of the EEG channel acquisition set up (58 EEG channels).** The three channel clusters used in  
 183 statistical data analysis are highlighted at different colors (frontal – blue, central – green, parieto-occipital – red).

## 184 185 **Data analysis**

186 The data analysis was performed offline using Matlab (MathWorks) and the EEGLAB toolbox  
 187 (version 13.5.4b) (Delorme and Makeig 2004). The signals were re-referenced to the average  
 188 signal of the earlobes channels and filtered between 0.5 Hz and 70 Hz and segmented in epochs  
 189 locked to each stimulation condition/imagery task onset. Then, we applied an eye movement  
 190 related artifact correction procedure based on independent component analysis (ICA) of all  
 191 electrode data (including the EOG channels). Artifact components were identified using ICA and  
 192 these components examined based on their correlation with the EOG electrodes and on the scalp  
 193 topography (increased activity distribution) and removed from the data (Keren *et al* 2010).  
 194 Signals were also corrected for possible artifacts related to body movement or muscle tension,  
 195 which were marked and excluded from further analysis. After artifact rejection we were able to

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3 196 keep more than 50 epochs for each stimulation condition/imagery task, except for the imagery  
4 data of one participant. For the data analysis of visual motion stimulation, we used a baseline  
5 197 taken from the last 500 ms of pre-stimulus time (last 500 ms of static dot condition before the  
6 motion conditions). For visual motion imagery data, the baseline was based on the last 500 ms of  
7 198 motion conditions). For visual motion imagery data, the baseline was based on the last 500 ms of  
8 the static dot imagery period.  
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12 201 We performed time-frequency analyses of the imagery data and of the stimulation data (as a  
13 control study). Mean event-related changes in spectral power (from baseline) at each time during  
14 202 the epochs and at each frequency were analyzed using the event-related spectral perturbation  
15 203 (ERSP) method (Makeig, 1993). ERSP analyses were performed for frequencies ranging from 3  
16 204 to 50 Hz for all channels by applying Morlet wavelets with incremental cycles (2 cycles at 3 Hz,  
17 205 up to 27 at 50 Hz) resulting in 200 time points. To visualize power changes across the frequency  
18 206 range, the mean baseline log power spectrum from each spectral estimate was subtracted  
19 207 producing the baseline-normalized ERSP. Significance of deviations from baseline power was  
20 208 assessed using a bootstrap method. ERSP group results were analyzed at  $P = 0.05$  (Delorme and  
21 209 Makeig 2004).  
22 210

23 211 In order to understand the main differences for specific frequency bands between stimulation  
24 212 conditions and between imagery tasks, the mean power of EEG signal from all channels over the  
25 213 500 ms and 1500 ms of all epochs was calculated for the three stimulation conditions and for the  
26 214 three imagery tasks. The power spectral density (PSD) was estimated via the Welch's method  
27 215 which uses the Fast Fourier Transform (FFT) (Welch, 1967).  
28 216

29 217 We also performed source localization of the EEG data based in sLORETA (standardized low  
30 218 resolution brain electromagnetic tomography) software package (Pascual-Marqui, 2002). This  
31 219 method employs the current density estimate given by the minimum norm solution. The  
32 220 localization inference is based on standardized values of the current density estimates (Pascual-  
33 221 Marqui *et al* 1994, Pascual-Marqui 2002). The source analysis was performed to infer about the  
34 222 biological significance of the most relevant frequency data.  
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### 37 225 **Imagery data classification**

38 226 In order to verify if the three employed imagery tasks may lead to successful achievement of  
39 three classes of control in BCI applications, we attempted to classify these classes using a  
40 reduced number of channels and features.  
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3 227 We used pre-processed (filtered, re-referenced and with artifact correction) trials, with one  
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5 228 second each (from 0.5 to 1.5 of each trial). The duration of the trials used for classification was  
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7 229 chosen to be the same to the three conditions and to not include the reminder beep. The initial 0.5  
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9 230 seconds after the auditory instruction cue were also excluded.

10 231 The features were extracted from a set of channels empirically chosen based on the group  
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12 232 power spectrum per channel. The relative spectral power (RSP) of the frequency band from 7 Hz  
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14 233 to 15 Hz was extracted from 6 EEG channels (F3, F5, FC3, FC5, C3, C5). The frequency band  
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16 234 was chosen in order to take into account the variability in alpha activity definition across  
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18 235 different subjects (Haegens *et al* 2014). These 6 features from 50 trials of each imagery task  
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20 236 were normalized and then classified using a support vector machine (SVM).

21 237 As shown in previous studies (Khalighi *et al* 2013, Sousa *et al* 2015), the RSP provides some  
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23 238 of the most relevant information from the EEG signals to classification. The RSP of each  
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25 239 frequency-band is given by the ratio between the band spectral power and the total spectral  
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27 240 power (Mormann *et al* 2007). The spectral power was calculated based on FFT. To avoid  
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29 241 features in greater numeric ranges dominating those in smaller numeric ranges, each feature was  
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31 242 independently normalized dividing its value by the difference between maximum and minimum  
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33 243 of the feature across training trials.

34 244 The classifier was trained and tested using leave-one out cross-validation (LOOCV). The  
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36 245 Libsvm toolbox (Chang and Lin 2011) with a sigmoid kernel was used in classification. The  
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38 246 sigmoid degree and  $C$  parameter of SVM were optimized between 0 and 5 for each participant  
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40 247 model classification. The classifier was trained and tested individually per participant. In order to  
41  
42 248 characterize the trial-by-trial classification performance, some well-known measures such as  
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44 249 balanced accuracy, sensitivity and specificity were used.

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## 46 251 **Statistical Analysis**

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48 252 Statistical analyses were performed to compare the group mean EEG power for the most relevant  
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50 253 frequency bands found in the evoked brain responses during the three during the three imagery  
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52 254 tasks and during the stimulation conditions (as a control study). The Friedman's test was applied  
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54 255 to verify the presence of a main effect for each defined frequency band. Further, we computed  
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56 256 pairwise comparisons for stimulation condition/imagery task per EEG channel cluster using  
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58 257 Wilcoxon tests and applying the Dunn's correction for multiple comparisons. The EEG data  
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3 were organized in three channel clusters: frontal (anterior-frontal, frontal, fronto-temporal and  
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5 259 fronto-central channels), central (central, centro-parietal, temporal and tempo-parietal channels)  
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7 260 and parieto-occipital (parietal, parieto-occipital and occipital channels). Statistical analyses were  
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9 261 performed with the IBM (Armonk, NY) SPSS Statistics 22.0 software package.

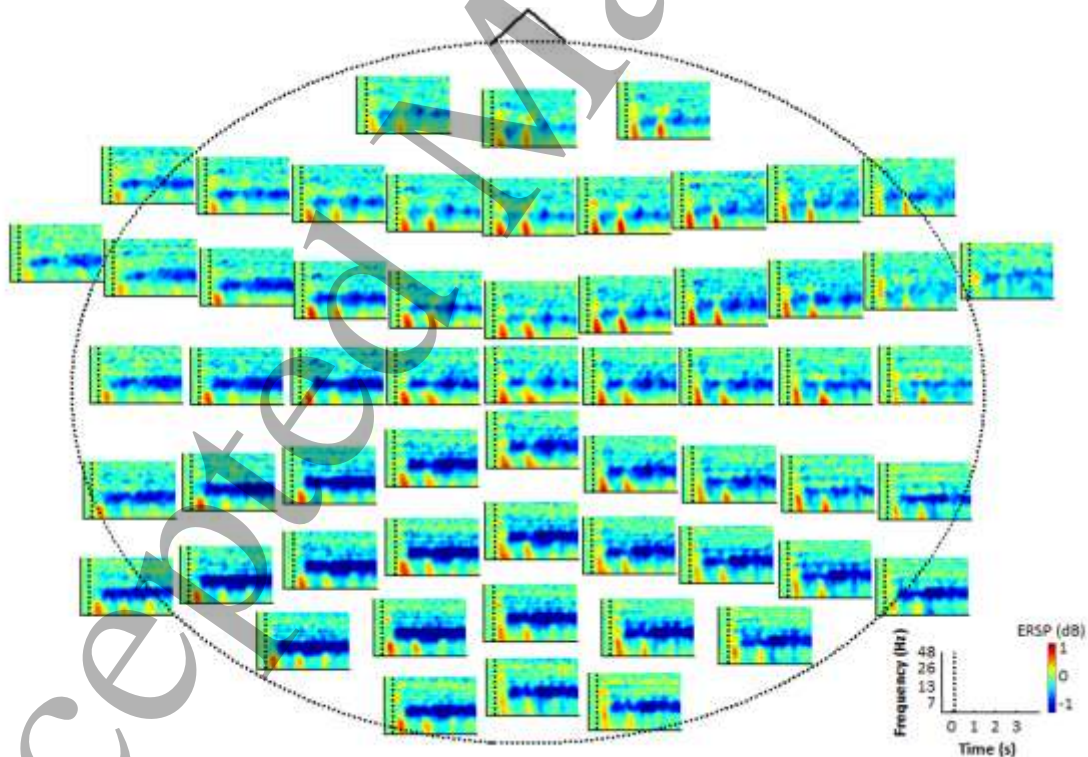
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## 264 Results

### 265 Visual motion stimulation

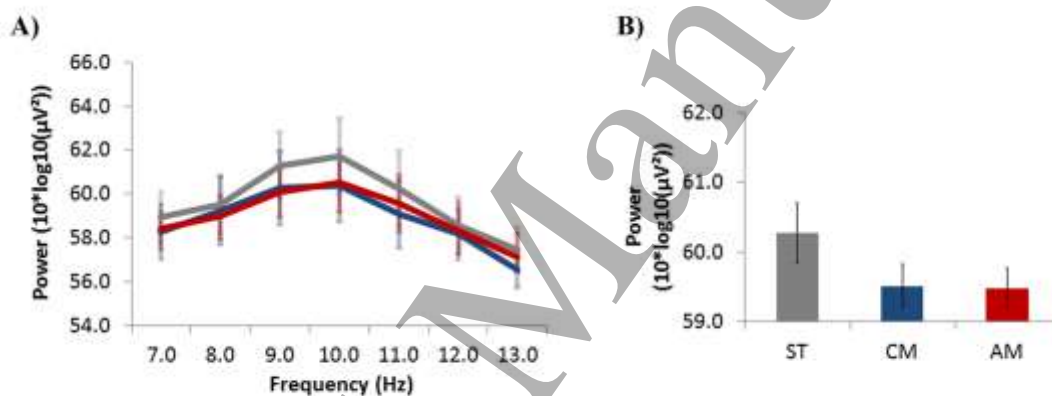
266 Comparing the evoked brain activation by the motion conditions to the static dot condition brain  
267 response (used as baseline) we found a significant decrease, as expected, of alpha-band power  
268 mainly in the parietal, parieto-occipital and occipital channels for visual moving stimuli  
269 conditions (figure 3).



270

271 **Figure 3. Brain responses to visual moving stimuli.** Group event-related spectral perturbation (ERSP) for  
272 frequencies between 5 Hz and 50 Hz across entire trials (from -0.5 second to 4 seconds) pooled for moving stimuli  
273 when compared to a no-motion stimulation condition (baseline). All shown ERSP values different from zero are  
274 significant at  $P = 0.05$ .

For the parieto-occipital channels cluster we found statistically significant main effects for the evoked mean alpha-band power during the different stimulation conditions ( $\chi_F^2(2) = 10.57$ ,  $P = 0.005$ ). The peak power frequency (10 Hz) is consistent across the brain responses to the different stimulation conditions and is within the conventional alpha-band (figure 4). The alpha-band power was significantly lower during both moving stimulation conditions (constant motion – CM:  $P = 0.01$ ; alternate motion – AM:  $P = 0.02$ ) than during the no-motion stimulation (static dot – ST). Concerning the frontal and central channel clusters we found no significant differences. In the mean of participants and parieto-occipital cluster of channels, the power spectrum of the evoked brain activity during the constant motion stimulation and the alternate motion stimulation is similar.



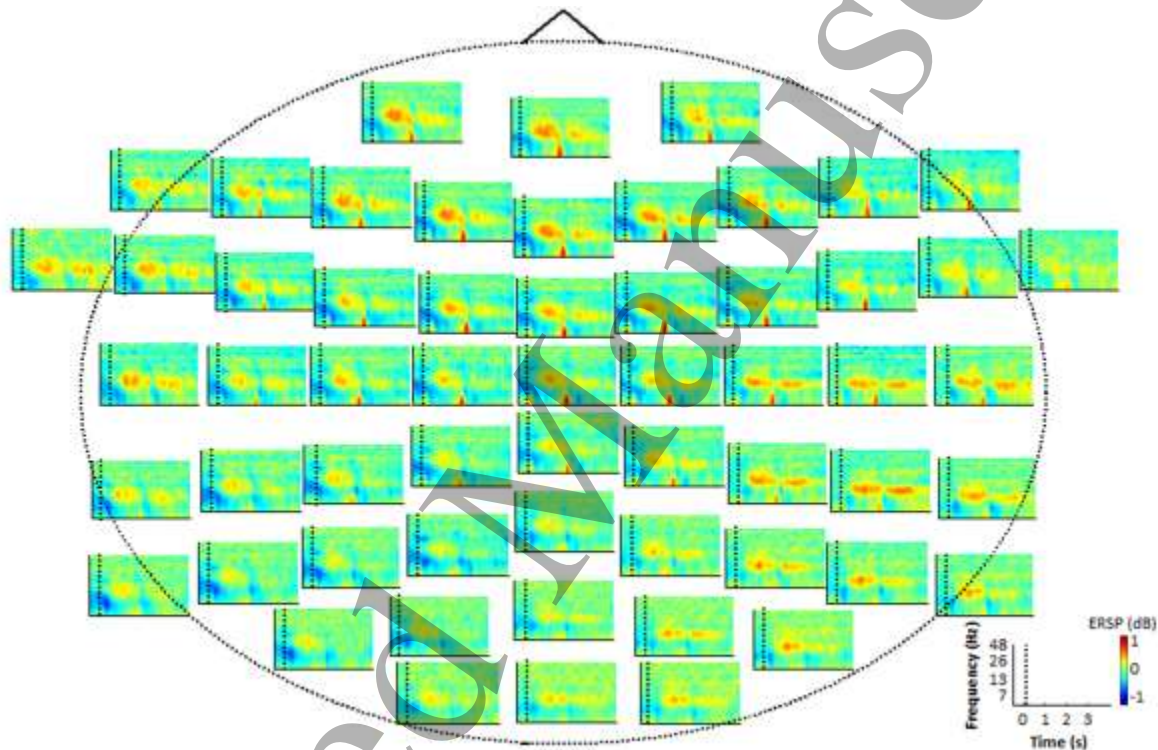
**Figure 4. Group mean alpha-band power according to stimulation conditions ( $\pm$  standard mean error).** Power spectrum of the evoked brain activity recorded in occipital channels cluster per stimulation condition (A) and its average from 8 Hz to 12 Hz (B). Color codes: red - alternate motion (AM), blue - constant motion (CM), gray - static dot (ST). The alpha-band power decreases significantly from no-motion to motion conditions (CM vs. ST,  $P = 0.01$ , corrected; AM vs. ST,  $P = 0.02$ , corrected).

## Visual motion imagery

The time-frequency analyses of the visual motion imagery tasks revealed an increase of the alpha power activity when compared to the baseline (imagery of a static dot), starting after the participants received the specific imagery instruction (figure 5). This effect is mainly evident for the frontal and central EEG channels, corroborating the notion that it is a different type of alpha activity as compared to the decreasing pattern seen for real stimulation conditions (figure 3). The ERSP of both visual motion imagery conditions show some noticeable differences (see on example in supplementary figure 1). The increase of the frontal alpha signal power seems to be



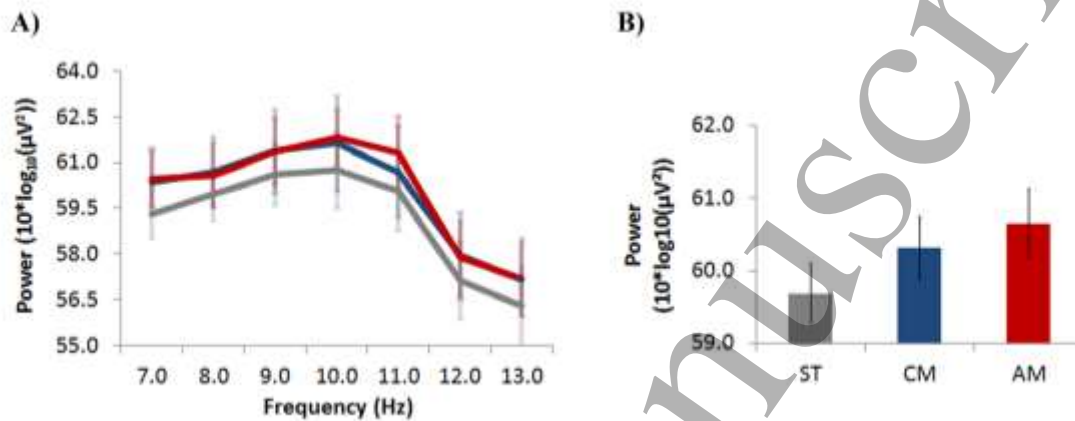
300 more sustained during alternated visual motion imagery than during continuous visual motion  
 301 imagery. Although these differences are not identified by standard statistical analysis (because  
 302 they not survive correction for multiple comparisons), they suggest the potential for being  
 303 separable using pattern recognition methods (see below the results). Furthermore, in some  
 304 fronto-central channels we also found a decrease of the frequency power around 26 Hz during  
 305 the alternated visual motion imagery. There is also a change in ERSP around 1.5 s (figure 5) that  
 306 is probably resulting from the reminder beep, since they are coincident.



307  
 308 **Figure 5. Brain responses to visual motion imagery.** Group event-related spectral perturbation (ERSP) for  
 309 frequencies between 5 Hz and 50 Hz across entire trials (from -0.5 second to 4 seconds) pooled for motion imagery  
 310 tasks when compared to a no-motion imagery task (baseline). Time 0 corresponds to auditory instruction end. All  
 311 shown ERSP values different from zero are significant at  $P = 0.05$ .

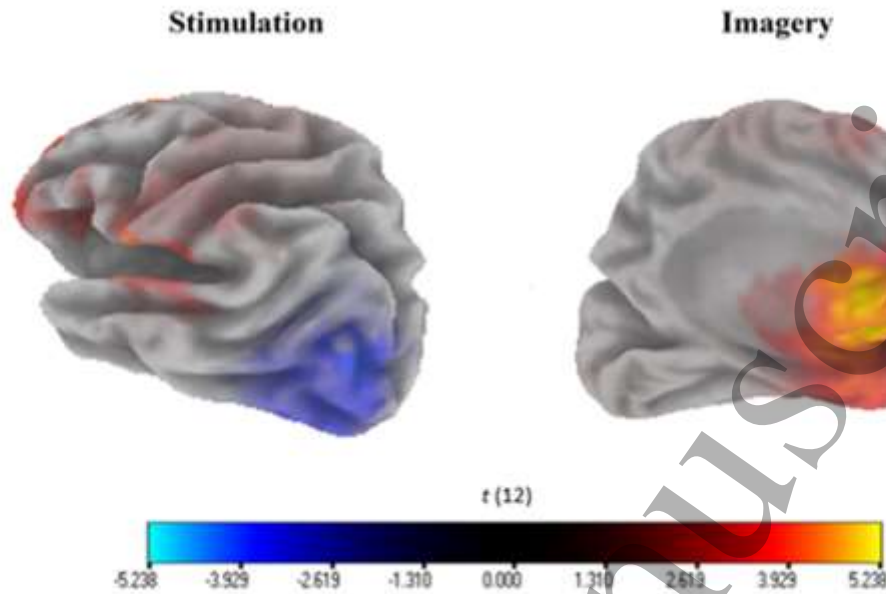
312 The mean alpha power (figure 6A) shows significant differences between the imagery tasks  
 313 on the frontal channel cluster ( $\chi^2_F(2) = 13.56$ ,  $P = 0.001$ ). Post hoc tests revealed the existence of  
 314 statistically significant differences between the average of alpha-band power evoked by imagery  
 315 of a static dot and by constant motion imagery ( $P = 0.007$ ) and between the average of alpha-  
 316 band power evoked by imagery of a static dot and by the alternate motion imagery ( $P = 0.003$ ).  
 317 The peak power frequency (around 10 Hz) is consistent across cortical responses during the  
 318 different imagery tasks. As stated above, although a classical statistical approach does not allow

for discrimination between both visual motion imagery strategies, the alpha-band power during the alternate motion imagery seems distinct from the pattern observed during constant motion imagery (mainly from 10 Hz to 12 Hz, figure 6B), suggesting that a multivariate analysis strategy based on SVM classification might be a viable approach (see below the results).



**Figure 6. Group mean alpha-band power according to each imagery task ( $\pm$  standard mean error).** Power spectrum of the evoked brain activity recorded in frontal channels cluster per imagery task (A) and its average at 10 Hz to 12 Hz for the three imagery tasks (B). The average results from 8 Hz to 12 Hz and representative individual results are presented as supplementary figure 2 and 4. Color codes: red - alternate motion imagery (AM), blue - constant motion imagery (CM), gray - static dot imagery (ST). The alpha-band power of the evoked brain activity recorded in frontal channels cluster differs significantly between the moving stimuli and the no-motion stimulus (CM vs. ST,  $P = 0.007$ , corrected; AM vs. ST,  $P = 0.003$ , corrected).

In order to understand the origin of the alpha activity increasing during the visual imagery of motion when compared to the visual imagery of a static dot, the EEG source localization for alpha-band (from 8 Hz to 12 Hz) and for two frequency sub-bands within the alpha range were examined (from 8 Hz to 10 Hz and from 10 to 12 Hz) applying the sLORETA method. The different frequency sub-bands analyzed within the alpha range were based on the notion that brain activity evoked by sensory stimulation or imaging peaks tend to differ (Klimesch 1999, Klimesch *et al* 2007). The source localization for activity evoked within this frequency-band during visual stimulation was also performed as a control. We used the comparison of visual moving stimuli (both motion conditions data combined) versus no-motion stimulus and the comparison of visual motion imagery (both visual motion imagery tasks data combined) versus no-motion visual imagery, using the data time interval from 0.5 seconds to 1.5 seconds.



342

343 **Figure 7. Source localization of the distinct alpha activity alterations during visual stimulation (control**  
 344 **experiment) and visual imagery performed using sLORETA. Visual stimulation elicits the well-known**  
 345 **posterior alpha desynchronization while imagery evokes anterior alpha synchronization.** The source found for  
 346 the decrease in alpha during visual moving stimuli, when compared to non-moving stimulus, is shown at the left  
 347 panel (maximum difference at the frequency-band from 8 Hz to 10 Hz). The right panel shows the identified  
 348 dominant frontal source for the increase in alpha during visual motion imagery when compared to non-motion  
 349 imagery (maximum difference at the frequency-band from 10 Hz to 12 Hz). The other views of each source analysis  
 350 are provided as supplementary figure 3.

351 The highest level of alpha activity during the visual motion imagery in relation to the imagery  
 352 of a static dot was found on the frontal lobe ( $t = 5.24$ , significant at  $P = 0.05$  for two-tailed  $t$  test)  
 353 at the frequency-band from 10 Hz to 12 Hz (figure 7, right). During the visual moving  
 354 stimulation the lowest recorded level of alpha activity (desynchronization) in relation to the non-  
 355 moving stimulus evoked brain activity was found in the occipital lobe at the frequency-band  
 356 from 8 Hz to 10 Hz ( $t = -4.52$ , significant at  $P = 0.05$ , two-tailed  $t$  test) (figure 7, left).

### 357 **Visual motion imagery classification**

358 The data were classified on trial-by-trial basis and using the relative spectral power of the  
 359 frequency band from 7 Hz to 15 Hz of 6 selected EEG anterior channels (F3, F5, FC3, FC5, C3,  
 360 and C5).

361 The results that reflect the success of distinction between each of the different combinations  
 362 of classes are presented in the confusion matrix (table 1). The balanced accuracy was also



363 calculated per class using a one-vs-all configuration based on those results. Once we have the  
 364 per-class accuracy for every class, we got the total balanced accuracy (table 2). On average the  
 365 three imagery tasks were classified with 87.64 % discrimination accuracy; 88.68 % on the  
 366 classification of static dot imagery, 88 % on the classification of constant motion imagery, and  
 367 86.23 % on the classification alternate motion imagery.

368 **Table 1. Confusion matrix of the total of classified EEG trials.** Classification results of 550 trials from each  
 369 imagery task - static dot imagery (ST), constant motion imagery (CM) and alternate motion imagery (AM).

		Classification		
		ST	CM	AM
Imagery trials	ST	459	38	53
	CM	27	465	58
	AM	40	56	454

370

371 **Table 2. Group classification performance  $\pm$  SEM.** Sensitivity (Sens), specificity (Spec) and balanced accuracy  
 372 (bACC) are presented as the group classification performance evaluation results for the imagery of a static dot (ST),  
 373 imagery of a dot with constant motion (CM) and imagery of a dot with alternate motion (AM).

	Sens	Spec	bACC
ST	83.45 $\pm$ 4.20	93.91 $\pm$ 1.41	88.68 $\pm$ 2.72
CM	84.55 $\pm$ 2.47	91.45 $\pm$ 1.96	88.00 $\pm$ 2.07
AM	82.55 $\pm$ 3.16	89.91 $\pm$ 1.93	86.23 $\pm$ 2.32
<i>Total</i>	<b>83.52 <math>\pm</math> 2.99</b>	<b>91.76 <math>\pm</math> 1.49</b>	<b>87.64 <math>\pm</math> 2.24</b>

374

375 The mean accuracy of classification was above the chance level for all participants (group  
 376 results significant at  $P = 0.001$  as revealed by a 2-tailed binomial test). From the eleven tested  
 377 participants, only two were classified with accuracy lower than 80 %. In the group confusion  
 378 matrix, it can be seen that the best performance of the classification algorithm was in the  
 379 distinction of constant motion imagery from no-motion imagery. On the other hand, the classifier  
 380 presented the highest number of misclassifications in distinguishing between constant motion  
 381 imagery trials and alternate motion imagery trials.

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## 384 Discussion

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3 385 In this study we tested the hypothesis that visual motion imagery of an external actuator can lead  
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5 386 to different discriminable classes (at least 3) of EEG signal modulation, potentially available for  
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7 387 BCI control. We used three visual motion imagery strategies which consisted on the imagery of  
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9 388 three visual conditions with different number of motion alternations. We were motivated by  
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11 389 findings showing that a different number of alternating sensory/perceptual signals (real or  
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13 390 imagined) lead to distinct neural responses (Tootell *et al* 1998, Huk and Heeger 2002, Larsson *et*  
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15 391 *al* 2006, Sousa *et al* 2016). A single-trial classification approach was tested and successfully  
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17 392 differentiated between each of the 3 imagery strategies while with standard statistical analysis we  
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19 393 were only able to find significant differences between the imagery of no-motion and the imagery  
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21 394 of visual motion conditions.

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23 395 Visual motion imagery evoked an anterior alpha pattern different than the visual motion  
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25 396 stimulation: in the first case we found an increase of alpha activity in fronto-central channels  
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27 397 while for the second case we found a decrease of alpha activity in parieto-occipital channels. In  
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29 398 other words, different functional forms of alpha activity were found for brain responses evoked  
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31 399 by visual motion imagery and visual motion stimulation.

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33 400 It is well known that visual stimulation elicits an occipital alpha power decrease, reflecting a  
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35 401 functional mechanism by which information is gated in visual cortex (Foxe and Snyder 2011,  
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37 402 Klimesch *et al* 2011, Schomer and Lopes Da Silva 2011, Klimesch 2012). We found similar  
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39 403 alpha power suppression, mainly in the parieto-occipital region, during visual motion stimulation  
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41 404 conditions. In contrast, a significant increase of alpha activity was found on the frontal channels  
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43 405 cluster during both visual motion imagery tasks. Some studies have suggested an increase of  
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45 406 frontal alpha activity during high internal processing demands such as during working memory  
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47 407 tasks (Sauseng *et al* 2005, Benedek *et al* 2011) and processes requiring imagination of stimulus  
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49 408 sequences (Cooper *et al* 2003). According to Klimesch *et al* (2007) and Schomer and Lopes Da  
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51 409 Silva (2011) the functional state where frontal alpha oscillations are dominant reflects a state of  
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53 410 reduced external information processing that is referred as a 'modulation gate', and the decrease  
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55 411 of occipital alpha power corresponds to a situation in which attention to external stimuli is  
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57 412 enabled. Moreover, previous studies suggest that mean frontal alpha amplitudes are enhanced for  
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59 413 more complex tasks (Cooper *et al* 2003). Thus, we suggest that the differences found between  
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414 the different motion alternation imagery tasks in which concerns frontal alpha activity, with a

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3 415 frequency peak above 10 Hz, can be related with the process of recovering the different  
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5 416 visualized motion sequence conditions.

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7 417 The source for the highest difference between the no-motion and motion visual imagery tasks  
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9 418 and between no-motion and motion visual stimulation conditions differs, as expected, on the  
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11 419 alpha sub-band frequency and location. These results are in agreement with previous studies that  
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13 420 have shown different patterns of alpha desynchronization/synchronization subdividing the alpha  
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15 421 frequency-band into different sub-bands (Klimesch 1999, Klimesch *et al* 2007). The source  
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17 422 localization results for the power increase during visual motion imagery can be related with the  
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19 423 role of frontal lobe in memory processes (Lenartowicz and McIntosh 2005). In animal studies  
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21 424 similar observations could be reported for memory tasks involving temporally complex visual  
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23 425 information (Gaffan and Wilson 2008).

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25 426 The potential value of imagery has been explored but mostly in the motor imagery domain,  
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27 427 i.e., imagery of motor movement visualization. Neuper and colleagues had shown that visual-  
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29 428 motor imagery did not reveal a clear spatial pattern and therefore was not prone for classification  
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31 429 (Neuper *et al* 2005). Furthermore, they also did not find parieto-occipital alpha  
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33 430 desynchronization during imagery. Our approach was different because we applied pure visual  
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35 431 imagery strategies of an external actuator (an object) motion which totally distinct from motor  
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37 432 imagery.

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39 433 Although a more classical statistical approach could not discern between the visual motion  
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41 434 imagery tasks with different number of alternations, the SVM based classification algorithm  
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43 435 performed a successful distinction between all visual motion imagery strategies supporting the  
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45 436 advantage of multivariate data analysis approaches (Lemm *et al* 2011). The high performance  
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47 437 achieved by the classifier reveals potentially distinguishable brain activity patterns according to  
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49 438 each imagery task. Therefore, our results suggest that visual motion imagery can be used to  
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51 439 achieve multiclass control systems with the potential for being implemented in BCI applications,  
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53 440 particularly in cases of mental disorders affecting attention, such as ADHD (Banca *et al* 2015,  
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55 441 DeBettencourt *et al* 2015, Ordikhani-Seyedlar *et al* 2016). Yet, real-time tests need to be carried  
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57 442 out in the future to confirm the feasibility of using our analysis approach in an online scenario.  
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59 443 Here we prioritized the optimization of signal to noise ratios in the experimental design as an  
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61 444 offline proof-of-concept study. In future experiments is necessary to take into account that BCI  
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63 445 users in non-controlled environments are exposed to diverse visual stimuli. Furthermore, the

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3 446 occurrence of some misclassification errors related to the differentiation between constant  
4 447 motion imagery and alternate motion imagery, suggest that there is room for task optimization.  
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## 9 10 **Conclusion**

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12 450 This study provides a proof-of-concept showing that it is possible to achieve up to three classes  
13 451 of control based on volitional brain activity modulation using pure visual motion imagery.

14 452 Results show that the frontal alpha increased during visual motion imagery of an external  
15 453 actuator with distinguishable patterns of activity, as assessed by a SVM classifier, depending on  
16 454 the level of motion alternation of the applied imagery strategy. A 3-class classifier was learned,  
17 455 using only a few channels, achieving 87.64% offline single-trial accuracy, which shows the  
18 456 potential relevance of frontal alpha activity in imagery processes and its potential application in  
19 457 BCI research of mental disorders affecting attention such as ADHD.  
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