

Exploiting the Circulant Structure of Tracking-by-detection

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Appendix B: Additional experimental results

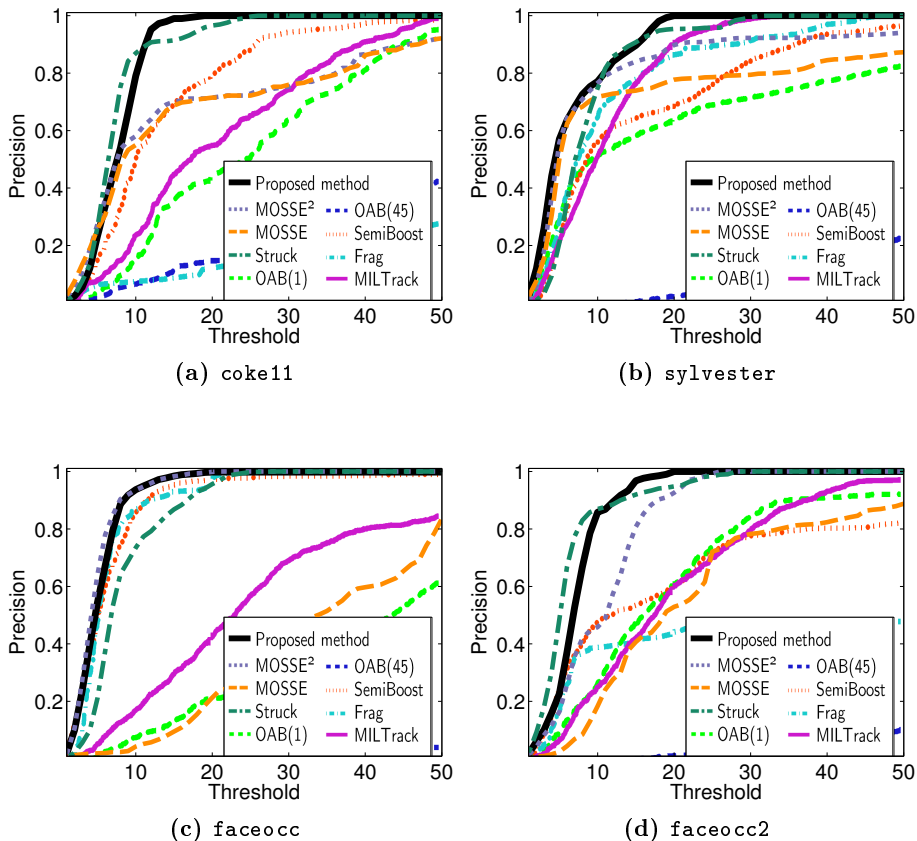
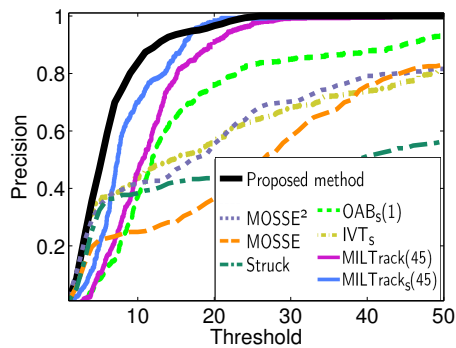
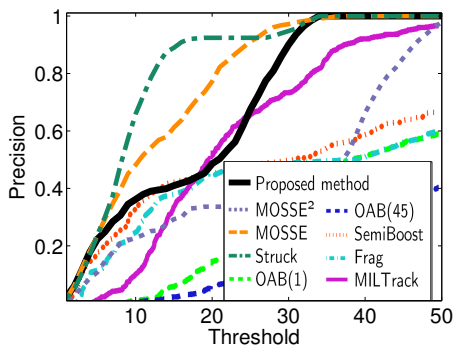


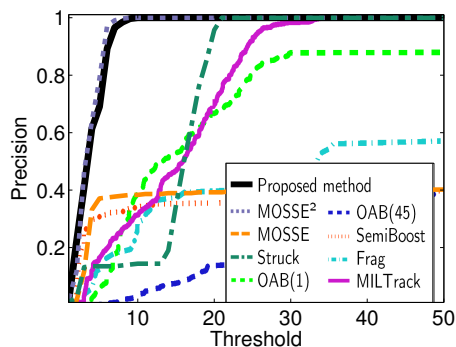
Fig. 1: Precisions plots for 4 sequences (percentage of frames where the predicted location is within the threshold of the ground truth). Best viewed in color.



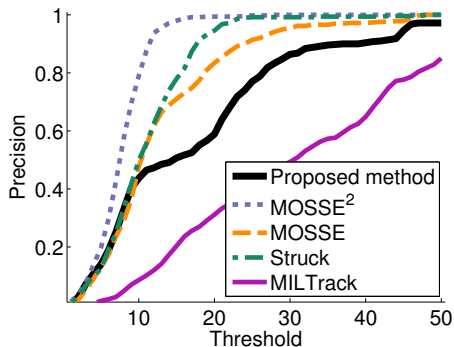
(a) cliffbar



(b) david



(c) dollar



(d) girl

Fig. 2: Precisions plots for 4 sequences (percentage of frames where the predicted location is within the threshold of the ground truth). Best viewed in color.

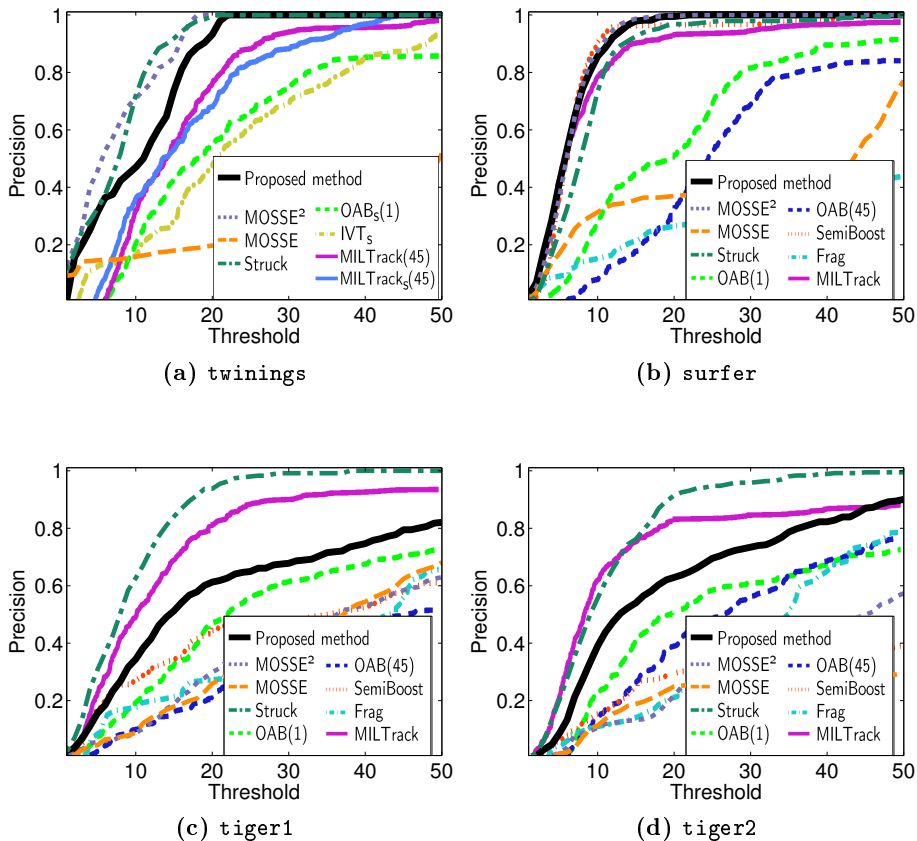


Fig. 3: Precisions plots for 4 sequences (percentage of frames where the predicted location is within the threshold of the ground truth). Best viewed in color.